AS480 Automatic Voltage Regulator (AVR)
SPECIFICATION, CONTROLS AND ACCESSORIES
# Table of Contents

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1 Description

1.1 Self-Excited AVR Controlled Alternators

1.1.1 Main Stator Powered AVR

The AVR provides closed loop control by sensing the alternator output voltage at the main stator windings and adjusting the exciter stator field strength. Voltage induced in the exciter rotor, rectified by the rotating diodes, magnetises the rotating main field which induces voltage in the main stator windings. A self-excited AVR receives power from the alternator output terminals.

<table>
<thead>
<tr>
<th>No.</th>
<th>Description</th>
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</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Main field (rotor)</td>
<td>5</td>
<td>AVR</td>
</tr>
<tr>
<td>2</td>
<td>Rotating diodes</td>
<td>6</td>
<td>Main armature (stator)</td>
</tr>
<tr>
<td>3</td>
<td>Exciter armature (rotor)</td>
<td>7</td>
<td>Output</td>
</tr>
<tr>
<td>4</td>
<td>Exciter field (stator)</td>
<td>8</td>
<td>Rotor shaft</td>
</tr>
</tbody>
</table>
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2 Specification

2.1 AS480 Technical Specification

- **Sensing and Power Input**
  - Voltage: 100 VAC to 264 VAC 1 phase
  - Frequency: 50 Hz to 60 Hz nominal

- **Power Output**
  - Voltage: maximum 82 VDC at 200 VAC input
  - Voltage: maximum 45 VDC at 110 VAC input
  - Current
    - continuous 5 A\(^1\)
    - transient 7.5 A for 10 s
  - Resistance: 15 $\Omega$ minimum

- **Regulation**
  - +/- 1.0%\(^2\)

- **Thermal Drift**
  - 0.03% per 1 °C change in AVR ambient temperature\(^3\)

- **Typical Response**
  - AVR response in 20 ms
  - Field current to 90% in 80 ms
  - Machine Volts to 97% in 300 ms

- **External Voltage Adjustment**
  - +/-10% with 1 k$\Omega$, 1 W trimmer\(^4\)
  - Fixed 82 k$\Omega$ enables 110 VAC sensing

- **Under-Frequency Protection**
  - Set point 94% to 98% Hz\(^5\)

- **Unit Power Dissipation**
  - 12 W maximum

- **Build-up Voltage**
  - 4 VAC at AVR terminals

- **Quadrature Droop Input**
  - 10 $\Omega$ burden
  - Maximum sensitivity: 0.07 A for 5% droop, zero power factor

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\(^1\) De-rate by 20% if mounted externally to alternator
\(^2\) With 4% engine governing
\(^3\) After 2 minutes warm-up.
\(^4\) Alternator de-rate may apply. Check with factory
\(^5\) Factory set, semi-sealed, jumper selectable
• Maximum input: 0.33 A

• **Over-Voltage Detection**
  • Set point: 67 VDC +/- 3% (fixed)
  • Time delay: 10 s to 15 s (fixed)

• **Environmental**
  • Vibration
    • 20 Hz to 100 Hz: 50 mm/sec
    • 100 Hz to 2 kHz: 3.3 g
  • Operating temperature: -40 °C to +70 °C
  • Relative Humidity 0 °C to 70 °C: 95%
  • Storage temperature: -55 °C to +80 °C

---

6 De-rate output current by 5% per 1 °C above 60 °C
7 Non condensing
## Controls

<table>
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Live electrical conductors can cause serious injury or death by electric shock and burns.  
To prevent injury and before removing covers over electrical conductors, isolate the generator set from all energy sources, remove stored energy and use lock out/tag out safety procedures. |

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### FIGURE 1. AS480 AVR CONTROLS

#### 3.2 Initial AVR Setup

**NOTICE**

The AVR must be setup only by authorised, trained service engineers. Do not exceed the designed safe operating voltage, shown on the alternator rating plate.

The AVR controls are set at the factory for initial running tests. Check that the AVR settings are compatible with your required output. Do not adjust controls that have been sealed. To set up a replacement AVR, follow these steps:

1. Stop and isolate the generator set.
2. Install and connect the AVR.
3. Turn the **AVR [VOLTS]** volts control Section 3.3 on page 7 fully counter-clockwise.
4. Turn the hand trimmer (if fitted) to 50%, the midway position.
5. Turn the **AVR [STAB]** stability control [Section 3.4 on page 8](#) to 50%, the midway position.

6. Connect a suitable voltmeter (0 to 300 VAC range) between one output phase and neutral.

7. Start the generator set with no load.

8. Adjust speed to nominal frequency (50 to 53 Hz or 60 to 63 Hz).

9. If the LDE is lit, adjust the **AVR [UFRO]** control [Section 3.5 on page 9](#).

10. Carefully turn **AVR [VOLTS]** control clockwise until the voltmeter shows rated voltage.

11. If voltage is unstable, adjust the **AVR [STAB]** stability control.

12. Re-adjust the **AVR [VOLTS]** control, as needed.

### 3.3 Adjust the AVR [VOLTS] Voltage Control

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<td>Hand trimmer terminals may be above earth potential. Do not ground any of the hand trimmer terminals. Grounding hand trimmer terminals could cause equipment damage.</td>
</tr>
</tbody>
</table>

**To set the output voltage AVR [VOLTS] control on the AVR:**

1. Check the alternator nameplate to confirm the designed safe operating voltage.

2. Set the **AVR [VOLTS]** control to 0%, the fully counter-clockwise position.

3. Check that the remote hand trimmer is fitted or terminals 1 and 2 are linked.

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<td>If a remote hand trimmer is connected, set it to 50%, the midway position.</td>
</tr>
</tbody>
</table>

4. Turn the **AVR [STAB]** control to 50%, the midway position.

5. Start the alternator and set at the correct operating speed.

6. If the red Light Emitting Diode (LED) is illuminated, refer to the Under Frequency Roll Off **AVR [UFRO]** adjustment.

7. Adjust the **AVR [VOLTS]** control slowly clockwise to increase the output voltage.
8. Adjust the output voltage to the desired nominal value (VAC).

9. If instability is present at rated voltage, refer to the AVR [STAB] adjustment, then adjust AVR [VOLTS] again, if necessary.

10. If a remote hand trimmer is connected, check its operation.

---

**NOTICE**

If the voltage is unstable, set the AVR stability before proceeding to Section 3.4 on page 8.

---

The AVR [VOLTS] control is now set.

### 3.4 Adjust the AVR [STAB] Stability Control

1. Check the nameplate to confirm the power rating of the alternator.

2. Check that the jumper link or rotary switch selection (depending on AVR type) matches the alternator power rating for optimal stability response.

3. Set the AVR [STAB] control to approximately 75% position.

4. Start the alternator and set at the correct operating speed.

5. Verify that the alternator voltage is within safe limits.

---

**NOTICE**

If the voltage is unstable, go immediately to step 5.

---

6. Adjust the AVR [STAB] control slowly counter-clockwise until the output voltage becomes unstable.

7. Adjust the AVR [STAB] control slowly clockwise until the voltage is stable.

8. Adjust the AVR [STAB] control a further 5% clockwise.

---

**NOTICE**

Readjust the voltage level if necessary (see Section 3.3 on page 7).

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The AVR [STAB] control is now set.
3.5 Adjust the AVR [UFRO] Under-Frequency Roll-Off Control

Below an adjustable frequency threshold ('knee' point), the AVR under-speed protection operates to reduce ('roll-off') the excitation voltage in proportion to alternator frequency. The AVR LED lights when UFRO operates.

1. Check the nameplate to confirm the frequency of the alternator.
2. Check that the jumper link or rotary switch selection (depending on AVR type) matches the alternator frequency.
3. Set the **AVR [UFRO]** control to 100%, the fully clockwise position.

4. Start the alternator and set at the correct operating speed.
5. Verify that the alternator voltage is correct and stable.

<table>
<thead>
<tr>
<th>NOTICE</th>
</tr>
</thead>
<tbody>
<tr>
<td>If the voltage is high / low / unstable, use method <strong>Section 3.3 on page 7</strong> or <strong>Section 3.4 on page 8</strong> before proceeding.</td>
</tr>
</tbody>
</table>

6. Reduce the alternator speed to approximately 95% of correct operating speed. i.e. 47.5 Hz for 50 Hz operation, 57.0 Hz for 60 Hz operation.
7. Adjust the **AVR [UFRO]** control slowly counter-clockwise until the AVR LED lights.

<table>
<thead>
<tr>
<th>Notice</th>
</tr>
</thead>
<tbody>
<tr>
<td>Do not go past the point at which the LED is just OFF.</td>
</tr>
</tbody>
</table>

8. Adjust the **AVR [UFRO]** control slowly clockwise until the AVR LED is just OFF.

9. Adjust the alternator speed back to 100% nominal. The LED should be off.

The **AVR [UFRO]** control is now set.
3.6 Adjust the AVR [DROOP] Voltage Droop Control for Parallel Operation

A correctly fitted and adjusted droop current transformer (CT) allows the alternator to share reactive current for stable parallel operation.

1. Mount the Droop CT to the correct phase lead of the main output windings of the alternator.
2. Connect the two secondary leads marked S1 and S2 from the CT to the terminals S1 and S2 of the AVR.
3. Turn the AVR [DROOP] control to the midway position.
4. Start the alternator(s) and set at the correct operating speed and voltage.
5. Parallel the alternator(s) according to installation rules and procedures.
6. Set the AVR [DROOP] control to produce the required balance between individual alternator output currents. Set the AVR droop off-load and then check the currents when the output load is applied, on-load.

7. If the individual alternator output currents rise (or fall) in an uncontrolled way, isolate and stop the alternators then check that:
   • The droop transformer is fitted to the correct phase and in the correct polarity (see the machine wiring diagrams).
   • The droop transformer secondary S1 and S2 leads are connected to the AVR terminals S1 and S2.
   • The droop transformer is the correct rating.

3.7 Adjust the AVR [EXC] Over-Excitation Control

<table>
<thead>
<tr>
<th>NOTICE</th>
</tr>
</thead>
<tbody>
<tr>
<td>The AVR [EXC] control is set and sealed at the factory to protect the alternator from over-excitation, usually caused by overload. Incorrect AVR [EXC] control setting could damage the alternator rotor components.</td>
</tr>
</tbody>
</table>

The AVR protects the alternator by removing excitation if it senses that the excitation voltage exceeds a threshold set by the AVR [EXC] control.

1. If the excitation voltage exceeds the over-excitation trip setting, the red LED on the AVR turns on.
2. After a short time, the AVR removes the excitation voltage and the red LED flashes (which can also indicate an over-voltage trip or UFRO operation).
3. Stop the alternator to reset the over-excitation condition.
4 Accessories

4.1 Alternator Protection Module

4.1.2 Description

The STAMFORD Alternator Protection Module (APM) is a three-phase over-voltage/under-voltage detector. The APM detects if any phase-to-neutral voltage exceeds an adjustable upper threshold or falls below a fixed lower threshold, and switches an internal relay if the fault persists for more than a few cycles (to avoid nuisance activation).

The changeover contact of the relay can be wired to a protective circuit to open a main circuit breaker, remove alternator excitation or stop the engine, for example. The APM is an inexpensive alternative to current monitoring short circuit protection, which requires three or more current transformers.

The APM operates for these faults:

- phase-to-neutral, by detecting under-voltage on the affected phase
- line-to-line, by detecting under-voltage on the affected phases or over-voltage on the third
- three-phase short circuit, by detecting under-voltage (separate no-voltage protection may also be triggered).
Key features include:

- Robust and reliable solid-state electronics
- Built-in relay to operate a protective circuit
- Short circuit protection without current transformers
- Simple connection to the alternator.

### 4.1.3 Specification

#### Input

- Voltage: 100 VAC to 360 VAC, 50 Hz to 60 Hz, 1 phase or 3 phase + neutral (APM 220 VAC version)
- Voltage: 175 VAC to 625 VAC, 50 Hz to 60 Hz, 3 phase + neutral (APM 380 VAC version)

#### Output

- Single pole changeover relay rating: 5 A @ 30 VDC, 5 A @ 240 VAC
- Power dissipation: 6 W maximum
- Pulse\(^6\) length: 200 ms minimum
- Pulse frequency: 3.2 s typical

#### Preset Range

- Under-voltage threshold: 110 VAC ± 10% (APM 220 VAC version)
- Under-voltage threshold: 190 VAC ± 10% (APM 380 VAC version)
- Over-voltage threshold: 245 VAC to 360 VAC, adjustable (APM 220 VAC version)
- Over-voltage threshold: 420 VAC to 625 VAC, adjustable (APM 380 VAC version)

#### Environmental

- Vibration: 30 mm/s @ 20 Hz to 100 Hz, 2 g @ 100 Hz to 2 kHz
- Relative humidity: 95%\(^9\)
- Storage temperature: -55 °C to +80 °C
- Operating temperature: -40 °C to +70 °C.

### 4.1.4 Controls

\[\text{\textbf{DANGER}}\]

**Live Electrical Conductors**

Live electrical conductors can cause serious injury or death by electric shock and burns. To prevent injury and before removing covers over electrical conductors, isolate the generator set from all energy sources, remove stored energy and use lock out/tag out safety procedures.

\[\text{\textbf{DANGER}}\]

**Live Electrical Conductors**

Live electrical conductors at output, AVR and AVR accessory terminals, and AVR heat sink can cause serious injury or death by electric shock and burns. To prevent injury, take suitable precautions to prevent contact with live conductors including personal protective equipment, insulation, barriers and insulated tools.

---

\(^6\) Pulsed output prevents overloading

\(^9\) Non-condensing
NOTICE

Refer to alternator wiring diagram for connection details. Mount the APM on a switchboard or bedplate, not in the alternator terminal box.
<table>
<thead>
<tr>
<th>Ref.</th>
<th>Control</th>
<th>Function</th>
<th>Turn potentiometer CLOCKWISE to</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Threshold</td>
<td>Adjust over-voltage threshold</td>
<td>increase voltage to operate relay</td>
</tr>
<tr>
<td>2</td>
<td>Sensing Input U, V, W, N</td>
<td>Connect to alternator output</td>
<td>N/A</td>
</tr>
<tr>
<td>3</td>
<td>Output relay contacts L, W</td>
<td>Connect to external control system</td>
<td>N/A</td>
</tr>
</tbody>
</table>

**FIGURE 2. ALTERNATOR PROTECTION MODULE CONTROLS**
4.2 Diode Failure Detector

4.2.2 Description

The STAMFORD Diode Failure Detector (DFD) senses ripple current in the exciter output caused by diode failure in short or open circuit, and switches an internal relay if it persists for 7 seconds.

The changeover contacts of the relay can be wired to provide a warning indication of diode failure or initiate an automatic shutdown.

Where the DFD triggers a warning, monitor the exciter field current or voltage and reduce load as necessary, so that the generator set can continue to run until a planned controlled shutdown to replace the diode.

Key features include:

- Robust and reliable solid-state electronics
- Built-in test function
- Selectable power supply
- Simple connection to the alternator.

4.2.3 Specification

- Sensing Input
  - Voltage: 0 VDC to 150 VDC
    Input resistance: 100 kΩ
    Sensitivity: 50 V peak

- Power Supply
  - Voltage: 12 VDC to 28 VDC
  - Voltage: 100 VAC to 140 VAC
- Voltage: 200 VAC to 280 VAC
- Current: 0.2 A maximum

**Output**
- Single pole changeover relay rating: 5 A @ 30 VDC, 5 A @ 240 VAC
- Isolation: 2 kV
- Volt-free contacts

**Time Delays**
- Response time: 7 s (approximately)

**Environmental**
- Vibration: 30 mm/s @ 20 Hz to 100 Hz, 2 g @ 100 Hz to 2 kHz
- Relative humidity: 95%\(^{10}\)
- Storage temperature: -55 °C to +80 °C
- Operating temperature: -40 °C to +70 °C.

### 4.2.4 Controls

<table>
<thead>
<tr>
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\(^{10}\) Non-condensing
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<tr>
<th>Ref.</th>
<th>Control</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Link : Test</td>
<td>Test DFD function</td>
</tr>
<tr>
<td></td>
<td>T1-T2</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>Sensing Input</td>
<td>Connect F2 in series between exciter stator and AVR</td>
</tr>
<tr>
<td></td>
<td>XX, XX</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>Output relay contacts</td>
<td>Connect to external warning or shutdown system</td>
</tr>
<tr>
<td></td>
<td>11-14 : Normally-open</td>
<td></td>
</tr>
<tr>
<td></td>
<td>11-12 : Normally-closed</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>Link : Supply voltage</td>
<td>Select VDC or VAC supply voltage</td>
</tr>
<tr>
<td></td>
<td>COM-DC : 12 VDC to 28 VDC</td>
<td></td>
</tr>
<tr>
<td></td>
<td>COM-120 : 100 VAC to 140 VAC</td>
<td></td>
</tr>
<tr>
<td></td>
<td>COM-240 : 200 VAC to 280 VAC</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>Power Supply</td>
<td>Connect VDC or VAC power supply</td>
</tr>
<tr>
<td></td>
<td>DC : VDC positive (VDC supply)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C : VDC negative (VDC supply)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>AC : P2 from PMG (VAC supply)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C : P3 from PMG (VAC supply)</td>
<td></td>
</tr>
</tbody>
</table>

**FIGURE 3. DIODE FAILURE DETECTOR CONTROLS**

11 disconnect to reset DFD
4.3 Excitation Loss Module

4.3.2 Description

A loss of alternator excitation during parallel operation will result in heavy circulating currents, pole-slipping (loss of synchronization), and torque/current surges and oscillation. The STAMFORD Excitation Loss Module (ELM) monitors the alternator AVR output and signals any sustained interruption to an integral relay to initiate an indication/alarm.

The ELM has been specially designed for use with all Stamford AVRs. It is powered independently from the engine battery at 12 VDC or 24 VDC. It operates by detecting the absence of the characteristic ‘rectifier ripple’ in the exciter field voltage. An optical isolator ensures complete electrical isolation between the exciter field circuit and the engine battery system. Any loss of AVR output is recognised immediately by the monitoring circuit, and if the interruption persists for more than about a second the module output energises an integral relay. The changeover contacts can either provide remote indication of the excitation failure or operate any other relay-fed protective device. The system incorporates a time delay to prevent spurious tripping on transients and an eight-second engine-start lock-out that can be overridden.

Key features include:

- Robust and reliable solid-state electronics
- Independently-powered from the engine battery
- Power supply is completely isolated from exciter field
- Engine-start lock-out time delay.

4.3.3 Specification

- Sensing Input
  - Voltage: 0 VDC to 150 VDC
  - Input resistance: 100 kΩ
  - Sensitivity: 50 V peak
• **Power Input**
  - Voltage: 10 VDC to 14 VDC (ELM 12V version)
  - Voltage: 20 VDC to 28 VDC (ELM 24V version)
  - Current: 25 mA max. in standby (both versions)
  - Relay on: 150 mA maximum (ELM 12V version)
  - Relay on: 60 mA maximum (ELM 24V version)

• **Output**
  - Single pole changeover relay rating: 5 A @ 30 VDC, 5 A @ 240 VAC
  - Power dissipation: 3 W maximum

• **Time Delays**
  - Response time: 1.5 s to 2 s
  - Power up delay: 8 s to 15 s

• **Environmental**
  - Vibration: 30 mm/s @ 20 Hz to 100 Hz, 2 g @ 100 Hz to 2 kHz
  - Relative humidity: 95%\textsuperscript{12}
  - Storage temperature: -55 °C to +80 °C
  - Operating temperature: -40 °C to +70 °C.

## 4.3.4 Controls

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<th>Function</th>
<th>Turn potentiometer CLOCKWISE to</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>DELAY</td>
<td>Adjust time delay</td>
<td>increase delay to operate relay</td>
</tr>
<tr>
<td>2</td>
<td>Sensing Input F1, F2</td>
<td>Connect to exciter stator</td>
<td>N/A</td>
</tr>
<tr>
<td>3</td>
<td>Output relay contacts</td>
<td>Connect to external control system</td>
<td>N/A</td>
</tr>
<tr>
<td></td>
<td>COM-NO : Normally-open</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>COM-NC : Normally-closed</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>Power Input B- : Battery</td>
<td>Connect to engine battery</td>
<td>N/A</td>
</tr>
<tr>
<td></td>
<td>negative</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>B+ : Battery positive</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**FIGURE 4. EXCITATION LOSS MODULE CONTROLS**
4.4 Remote Control Interface

4.4.1 Description

The STAMFORD Remote Control Interface (RCI) is used with a STAMFORD Automatic Voltage Regulator (AVR) or a STAMFORD Power Factor Controller (PFC3) to control the alternator voltage or power factor (respectively) remotely.

The RCI has two inputs which accept unipolar 4-20Ma or bipolar 0-10 volt signals to control alternator power factor from 0.7 lag to 0.7 lead or alternator voltage up to +/- 10%. The input circuitry is fully floating for maximum application flexibility. Loss of the control signal provides a default Unity Power Factor setting or returns the voltage to the AVR no-load setting.

The RCI allows the power factors of alternators running in parallel to be controlled automatically from a convenient remote location, to suit local site conditions.

The RCI allows the voltage of several alternators to be matched simultaneously with one signal, to allow voltage matching before paralleling.

Key features include:

- Robust and reliable solid-state electronics
- Industry standard interfaces to control equipment
- Selectable power supply from alternator output
- Simple connection to the alternator.

4.4.2 Specification

- **Control Input**
  - Voltage: 0 VDC to 10 VDC, input resistance 100 Ω
  - Current: 4 mA to 20 mA, input resistance 38 kΩ\(^1\)
  - Optical isolation: 1 kV input to output

- **Power Input**
  - Voltage: 110 VAC to 125 VAC, 50 Hz to 60 Hz
  - Voltage: 200 VAC to 230 VAC, 50 Hz to 60 Hz
  - Voltage: 231 VAC to 250 VAC, 50 Hz to 60 Hz
  - Voltage: 251 VAC to 290 VAC, 50 Hz to 60 Hz
  - Power: 5 VA

- **Output**
  - Single pole changeover relay rating: 5 A @ 30 VDC, 5 A @ 240 VAC
  - Optical isolation: 2 kV

- **Preset Range**
  - Power factor control: 0.7 lead (4 mA) to 0.7 lag (20 mA) or 0.7 lead (-10 VDC) to 0.7 lag (+10 VDC)\(^2\)

\(1\) Use twisted pair, screened cables separated from power. Apply control input smoothly with alternator at rest, from default 12 mA. To allow the PFC3 to compensate after voltage matching, return the control input smoothly to 12 mA in not less than 15 seconds.

\(2\) see **Figure 5** for response
• Voltage control: -10% (4 mA) to +10% (20 mA) or -10% (-10 VDC) to +10% (+10 VDC)\textsuperscript{15,16}

• Response time constant: less than 20 ms

• Environmental

  • Vibration: 50 mm/s @ 10 Hz to 100 Hz, 4.4 g @ 100 Hz to 300 Hz

  • Relative humidity: 95%\textsuperscript{17}

  • Storage temperature: -55 °C to +80 °C

  • Operating temperature: -40 °C to +70 °C.

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\textsuperscript{15} see Figure 6 for response

\textsuperscript{16} Depends on AVR type and VTRIM setting.

\textsuperscript{17} Non-condensing
4.4.3 Controls

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<thead>
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<th>DANGER</th>
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| **Live Electrical Conductors**  
Live electrical conductors can cause serious injury or death by electric shock and burns.  
To prevent injury and before removing covers over electrical conductors, isolate the generator set from all energy sources, remove stored energy and use lock out/tag out safety procedures. |

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| **Live Electrical Conductors**  
Live electrical conductors at output, AVR and AVR accessory terminals, and AVR heat sink can cause serious injury or death by electric shock and burns.  
To prevent injury, take suitable precautions to prevent contact with live conductors including personal protective equipment, insulation, barriers and insulated tools. |

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<th>NOTICE</th>
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<tr>
<td>Refer to alternator wiring diagram for connection details. Mount the RCI on a standard AVR chassis with anti-vibration mounts.</td>
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**FIGURE 7. REMOTE CONTROL INTERFACE CONTROLS**
4.5 **Hand Trimmer (for remote voltage adjustment)**

A hand trimmer can be fitted in a convenient position (typically in the generator set control panel) and connected to the AVR to provide fine adjustment of the alternator voltage. The hand trimmer value and the adjustment range obtained is as defined in the Technical Specification. Refer to wiring diagram before removing the shorting link and connecting the hand trimmer.

4.6 **Droop Transformer (for parallel operation – alternator to alternator)**

A droop transformer can be fitted in a defined position in the alternator main output wiring and connected to the AVR to enable parallel operation with other alternators. The adjustment range is as defined in the Technical Specification. Refer to wiring diagram before removing the shorting link and connecting the droop transformer. The droop transformer MUST be connected in the correct main output terminal for proper operation (details are as shown in the machine wiring diagram).

4.7 **Excitation Boost System (with AS480 AVR only)**

An add-on pilot winding and permanent-magnet rotor assembly is available to enhance the motor-starting and overload performance of the AS480 AVR. This is fitted to the non-drive-end bracket of the generator as a single integrated assembly and connects into the AVR via four ‘faston’ connections. During motor-starting or other heavy overloads the unit automatically provides additional excitation support as demanded by the AVR. An internal over-excitation system prevents prolonged overload from damaging the generator.
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