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S6L1D-H4 Wdg.13 - Technical Data Sheet

Standards

STAMFORD industrial alternators meet the requirements of the relevant parts of the IEC 60034 and the relevant sections of other international standards such as BS5000-3, ISO 8528-3, VDE 0530, NEMA MG1-32, CSA C22.2-100 and AS 60034. Other standards and certifications can be considered on request.

Quality Assurance

Alternators are manufactured using production procedures having a quality assurance level to BS EN ISO 9001.

Excitation and Voltage Regulators

Excitation System					
AVR Type	MX321/MX322	MX341	DECS150		
Voltage Regulation	± 0.5%	± 1%	± 0.25%		with 4% Engine Governing
AVR Power	PMG	PMG	PMG		

No Load Excitation Voltage (V)	12.9
No Load Excitation Current (A)	0.7
Full Load Excitation Voltage (V)	49
Full Load Excitation Current (A)	2.5
Exciter Time Constant (seconds)	0.16

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Electrical Data				
Insulation System	H			
Stator Winding	Double Layer Concentric			
Winding Pitch	2/3			
Winding Leads	6			
Winding Number	13			
Number of Poles	4			
IP Rating	IP23			
RFI Suppression	BS EN 61000-6-2 & BS EN 61000-6-4,VDE 0875G, VDE 0875N. Refer to factory for others			
Waveform Distortion	NO LOAD < 1.5% NON-DISTORTING BALANCED LINEAR LOAD < 5.0%			
Short Circuit Ratio	1/Xd			
Steady State X/R Ratio	27.19			
60 Hz				
Telephone Interference	TIF<50			
Cooling Air Flow	2.27 m³/sec			
Voltage Star (V)	380	400	416	-
Voltage Parallel Star (V)	-	-	-	-
Voltage Delta (V)	-	-	-	-
kVA Base Rating (Class H) for Reactance Values (kVA)	1560	1560	1560	-
Saturated Values in Per Unit at Base Ratings and Voltages				
Xd Dir. Axis Synchronous	2.29	2.06	1.91	-
X'd Dir. Axis Transient	0.14	0.12	0.11	-
X"d Dir. Axis Subtransient	0.11	0.10	0.09	-
Xq Quad. Axis Reactance	1.93	1.74	1.61	-
X"q Quad. Axis Subtransient	0.29	0.26	0.24	-
XL Stator Leakage Reactance	0.06	0.05	0.05	-
X2 Negative Sequence Reactance	0.16	0.14	0.13	-
X0 Zero Sequence Reactance	0.02	0.02	0.02	-
Unsaturated Values in Per Unit at Base Ratings and Voltages				
Xd Dir. Axis Synchronous	2.74	2.48	2.29	-
X'd Dir. Axis Transient	0.16	0.14	0.13	-
X"d Dir. Axis Subtransient	0.13	0.12	0.11	-
Xq Quad. Axis Reactance	1.99	1.79	1.66	-
X"q Quad. Axis Subtransient	0.35	0.31	0.29	-
XL Stator Leakage Reactance	0.07	0.06	0.06	-
Xlr Rotor Leakage Reactance	0.08	0.08	0.07	-
X2 Negative Sequence Reactance	0.19	0.17	0.16	-
X0 Zero Sequence Reactance	0.03	0.02	0.02	-

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Time Constants (Seconds)		
T'd Transient Time Const.	0.088	
T''d Sub-Transient Time Const.	0.012	
T'do O.C. Field Time Const.	4.026	
Ta Armature Time Const.	0.021	
T''q Sub-Transient Time Const.	0.0117	
Resistances in Ohms (Ω) at 22^{0}C		
Stator Winding Resistance (Ra), per phase for series connected	0.00100	
Rotor Winding Resistance (Rf)	2.42	
Exciter Stator Winding Resistance	19.56	
Exciter Rotor Winding Resistance per phase	0.1	
PMG Phase Resistance (Rpmg) per phase	1.91	
Positive Sequence Resistance (R1)	0.0013	
Negative Sequence Resistance (R2)	0.0014	
Zero Sequence Resistance (R0)	0.0013	
Saturation Factors	416V	
SG1.0	0.813	
SG1.2	2.861	
Mechanical Data		
Shaft and Keys	All alternator rotors are dynamically balanced to better than ISO 21940-11 Grade 2.5 for minimum vibration in operation. Two bearing generators are balanced with a half key.	
	1 Bearing	2 Bearing
SAE Adaptor	SAE0,00	SAE0,00
Moment of Inertia	28.237 kgm²	28 kgm²
Weight Wound Stator	1361kg	1361kg
Weight Wound Rotor	1116kg	1073kg
Weight Complete Alternator	2836kg	2962kg
Shipping weight in a Crate	2881kg	3007kg
Packing Crate Size	180x105x153(cm)	180x105x153(cm)
Maximum Over Speed	2250 RPM for two minutes	
Bearing Drive End	-	BALL 6224
Bearing Non-Drive End	BALL 6317	BALL 6317

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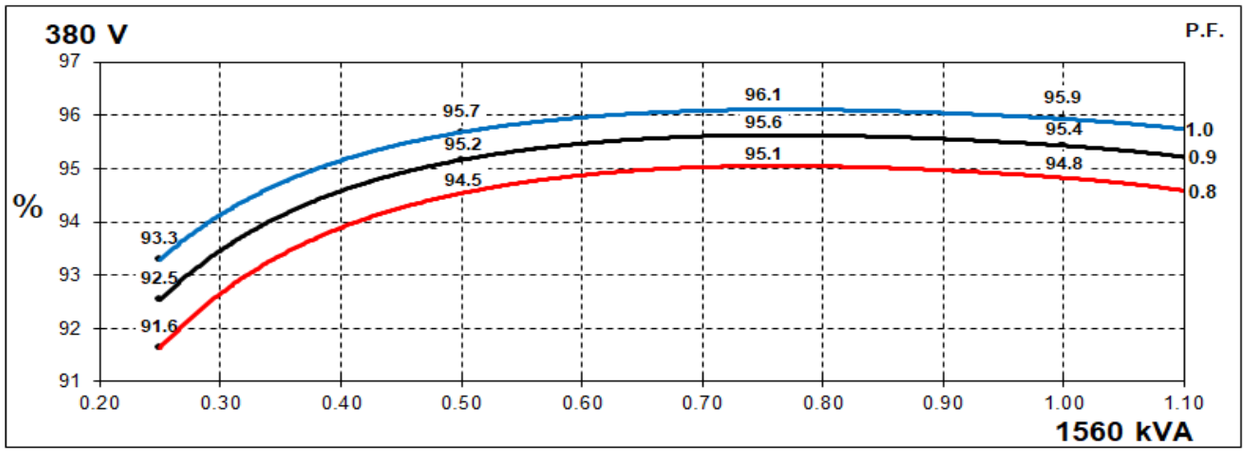
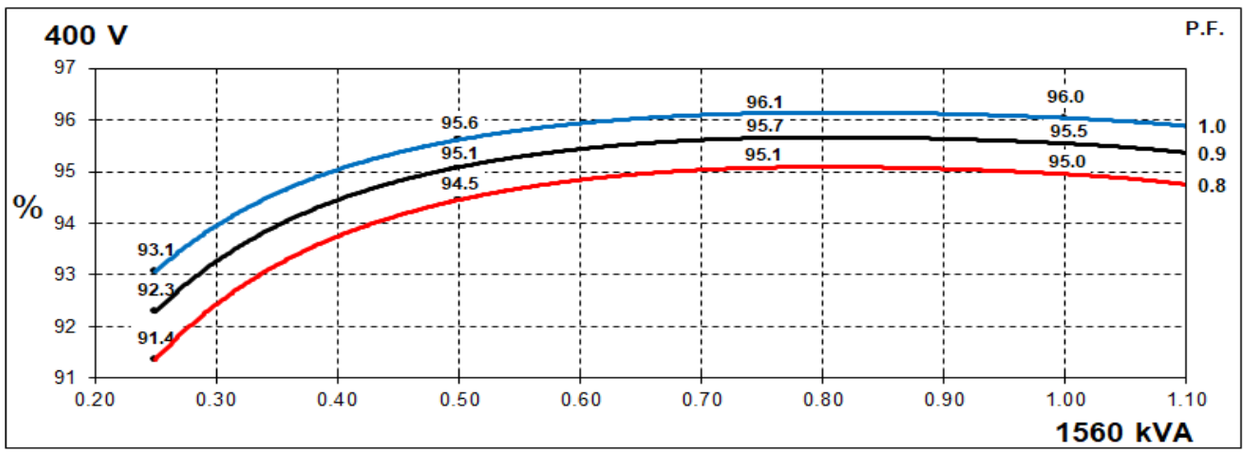
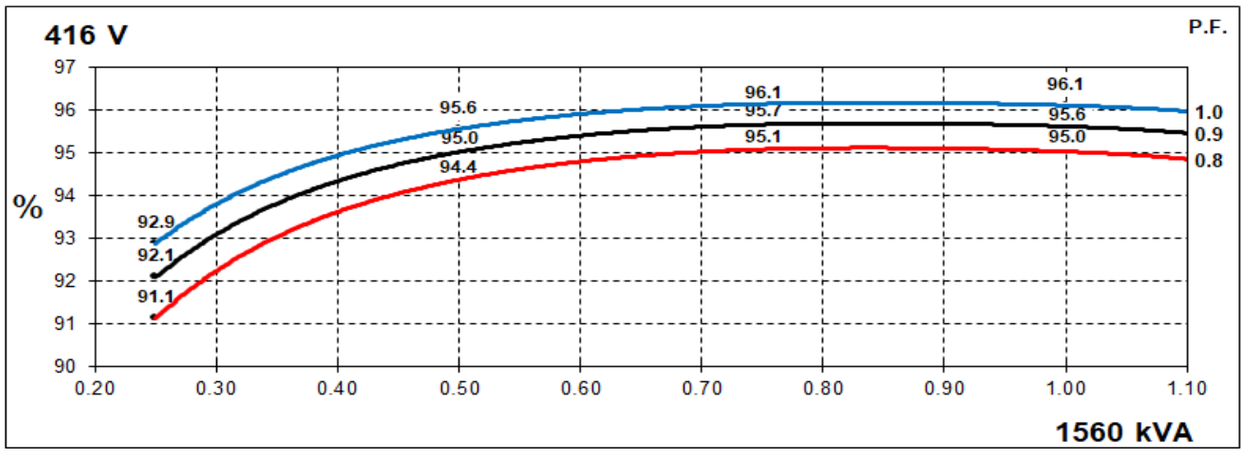
THREE PHASE EFFICIENCY CURVES

60Hz







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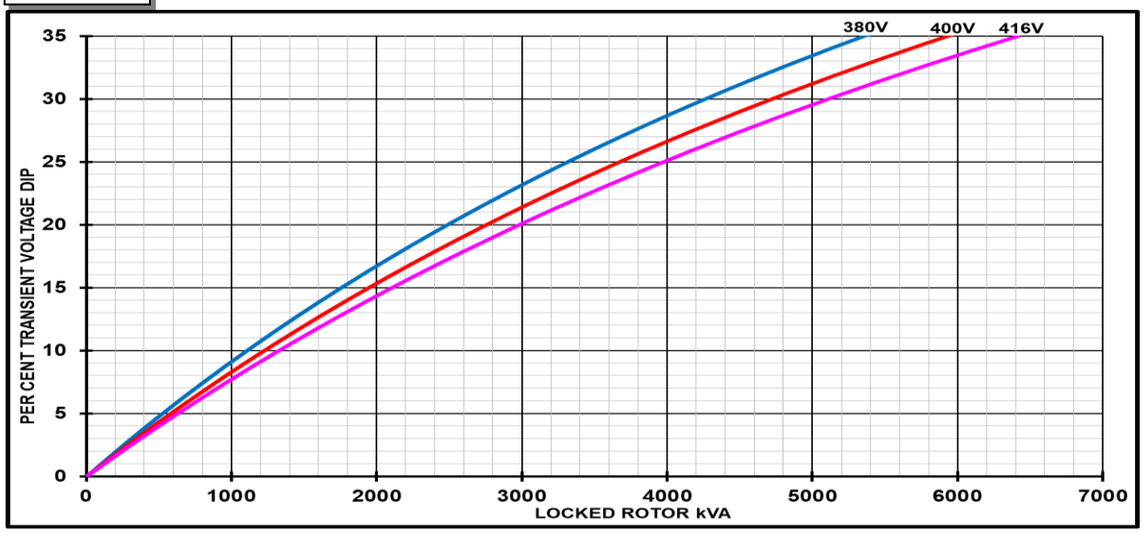
Locked Rotor Motor Starting Curves - Separately Excited

60Hz



Transient Voltage Dip Scaling Factor	
Lagging PF	Scaling Factor
<= 0.4	1.00
0.5	0.95
0.6	0.90
0.7	0.86
0.8	0.83
0.9	0.75
0.95	0.70
1	0.65

Transient Voltage Rise Scaling Factor	
Lagging PF	Scaling Factor
<= 0.4	1.25
0.5	1.20
0.6	1.15
0.7	1.10
> 0.7	1.00

Note: To determine % Transient Voltage Dip or Voltage Rise at various PF, multiply the % Voltage Dip from the curve directly by the Scaling Factor.

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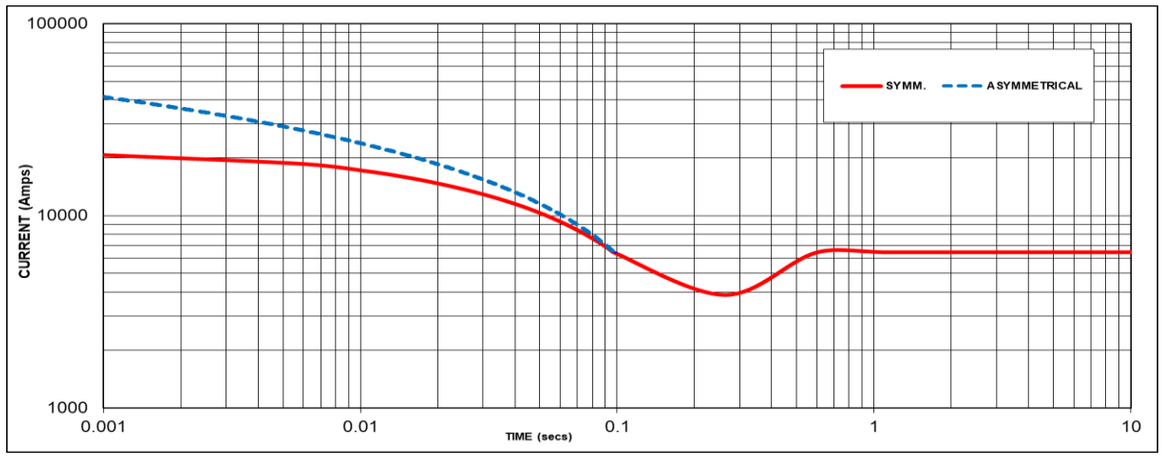
Three-phase Short Circuit Decrement Curve - Separately Excited

60Hz



Sustained Short Circuit = 6456 Amps

Note 1
The following multiplication factors should be used to adjust the values from curve between time 0.001 seconds and the minimum current point in respect of nominal operating voltage :

50Hz		60Hz	
Voltage	Factor	Voltage	Factor
-	-	380V	X 1.00
-	-	400V	X 1.05
-	-	416V	X 1.09
-	-	-	-

The sustained current value is constant irrespective of voltage level

If MX322 or digital AVR is used, the sustained short-circuit current value is to be multiplied by a factor of 1.1.

Note 2
The following multiplication factor should be used to convert the values calculated in accordance with NOTE 1 to those applicable to the various types of short circuit :

	3-phase	2-phase L-L	1-phase L-N
Instantaneous	x 1.00	x 0.87	x 1.30
Minimum	x 1.00	x 1.80	x 3.20
Sustained	x 1.00	x 1.50	x 2.50
Max. sustained duration	10 sec.	5 sec.	2 sec.

All other times are unchanged

Note 3
Curves are drawn for Star connections under no-load excitation at rated speeds. For other connection (where applicable) the following multipliers should be applied to current values as shown :
Parallel Star = Curve current value X 2
Series Delta = Curve current value X 1.732

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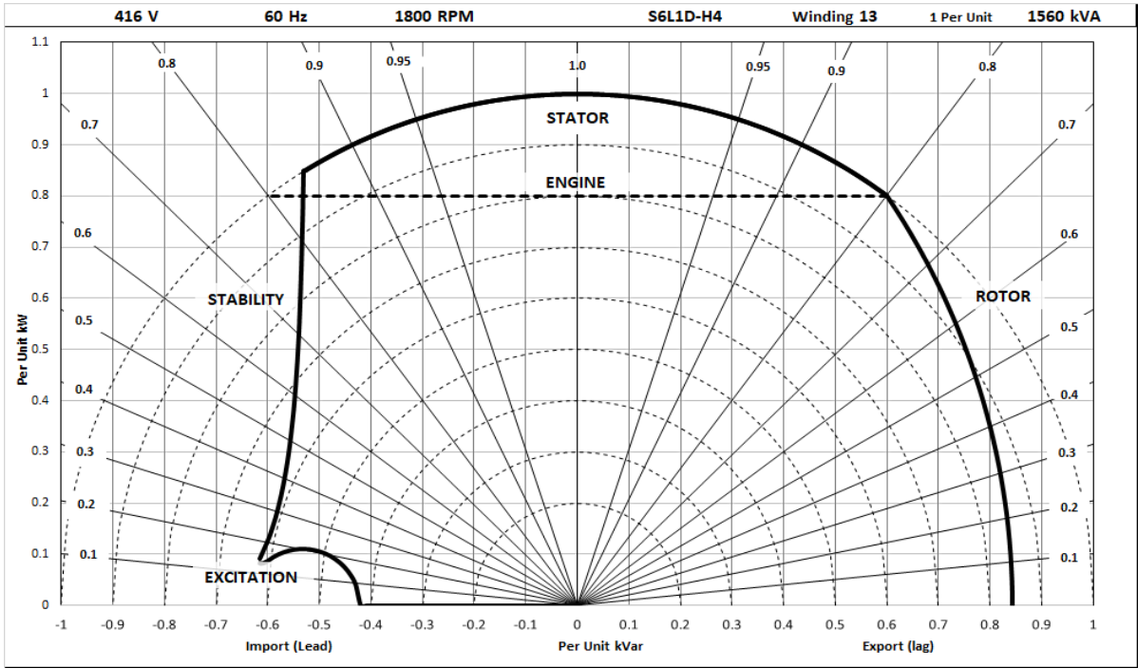
Typical Alternator Operating Charts

416V/60Hz



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RATINGS AT 0.8 POWER FACTOR

	Class - Temp Rise	Standby - 163/27°C	Standby - 150/40°C	Cont. H - 125/40°C	Cont. F - 105/40°C
50 Hz	Star (V)	N/A	N/A	N/A	N/A
	Parallel Star (V)	N/A	N/A	N/A	N/A
	Delta (V)	N/A	N/A	N/A	N/A
	kVA	N/A	N/A	N/A	N/A
	kW	N/A	N/A	N/A	N/A
	Efficiency (%)	N/A	N/A	N/A	N/A
	kW Input	N/A	N/A	N/A	N/A

60 Hz	Star (V)	380	400	416	N/A	380	400	416	N/A	380	400	416	N/A	380	400	416	N/A
	Parallel Star (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	Delta (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	kVA	1670	1670	1670	N/A	1625	1625	1625	N/A	1560	1560	1560	N/A	1455	1455	1455	N/A
	kW	1336	1336	1336	N/A	1300	1300	1300	N/A	1248	1248	1248	N/A	1164	1164	1164	N/A
	Efficiency (%)	94.7	94.8	94.9	N/A	94.7	94.9	95.0	N/A	94.8	95.0	95.0	N/A	94.9	95.0	95.1	N/A
	kW Input	1411	1409	1407	N/A	1372	1370	1369	N/A	1316	1314	1313	N/A	1226	1225	1224	N/A

De-rates

All values tabulated above are subject to the following reductions:

- 5% when air inlet filters are fitted
- 3% for every 500 meters by which the operating altitude exceeds 1000 meters above mean sea level
- 3% for every 5°C by which the operational ambient temperature exceeds 40°C @ Class H temperature rise (please refer to applications for ambient temperature de-rates at other temperature rise classes)
- For marine alternators, 3% for every 5°C by which the operational ambient temperature exceeds 50°C
- For any other operating conditions impacting the cooling circuit please refer to applications

Note: Requirement for operating in an ambient exceeding 60°C and altitude exceeding 4000 meters (for <690V) or 1500 meters (for >690V) must be referred to applications.

Dimensional and Torsional Drawing

For dimensional and torsional information please refer to the alternator General Arrangement and rotor drawings available on our website (http://stamford-avk.com/)

Note: Continuous development of our products means that the information contained in our data sheets can change without notice, and specifications should always be confirmed with Cummins Generator Technologies prior to purchase.

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