

STAMFORD®

S6L1D-D4 Wdg.311/312 - Technical Data Sheet

Standards

STAMFORD industrial alternators meet the requirements of the relevant parts of the IEC 60034 and the relevant sections of other international standards such as BS5000-3, ISO 8528-3, VDE 0530, NEMA MG1-32, CSA C22.2-100 and AS 60034. Other standards and certifications can be considered on request.

Quality Assurance

Alternators are manufactured using production procedures having a quality assurance level to BS EN ISO 9001.



Excitation and Voltage Regulators

Excitation System					
AVR Type	MX341	MX321/MX322	DECS100	DECS150	
Voltage Regulation	± 1%	± 0.5%	± 0.25%	± 0.25%	with 4% Engine Governing
AVR Power	PMG	PMG	PMG	PMG	

No Load Excitation Voltage (V)	16 - 15.2
No Load Excitation Current (A)	0.87 - 0.82
Full Load Excitation Voltage (V)	59
Full Load Excitation Current (A)	2.9
Exciter Time Constant (seconds)	0.17

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Electrical Data								
Insulation System	H							
Stator Winding	Double Layer Concentric							
Winding Pitch	2/3							
Winding Leads	12/6							
Winding Number	311/312							
Number of Poles	4							
IP Rating	IP23							
RFI Suppression	BS EN 61000-6-2 & BS EN 61000-6-4, VDE 0875G, VDE 0875N. Refer to factory for others							
Waveform Distortion	NO LOAD < 1.5% NON-DISTORTING BALANCED LINEAR LOAD < 5.0%							
Short Circuit Ratio	1/Xd							
Steady State X/R Ratio	19.93							
	50 Hz				60 Hz			
Telephone Interference	THF<2%				TIF<50			
Cooling Air Flow	1.42 m³/sec				1.71 m³/sec			
Voltage Series Star (V)	380	400	415	440	416	440	460	480
Voltage Parallel Star (V)*	190	200	208	220	208	220	230	240
Voltage Delta (V)	220	230	240	254	240	254	266	277
kVA Base Rating (Class H) for Reactance Values (kVA)	910	940	940	875	1025	1063	1075	1125
Saturated Values in Per Unit at Base Ratings and Voltages								
Xd Dir. Axis Synchronous	2.027	1.890	1.756	1.454	2.287	2.120	1.961	1.885
X'd Dir. Axis Transient	0.146	0.136	0.126	0.105	0.165	0.153	0.141	0.136
X''d Dir. Axis Subtransient	0.118	0.110	0.102	0.085	0.133	0.123	0.114	0.110
Xq Quad. Axis Reactance	1.826	1.702	1.581	1.309	2.059	1.909	1.766	1.697
X''q Quad. Axis Subtransient	0.285	0.266	0.247	0.205	0.322	0.298	0.276	0.265
XL Stator Leakage Reactance	0.067	0.062	0.058	0.048	0.075	0.070	0.065	0.062
X2 Negative Sequence Reactance	0.175	0.163	0.151	0.125	0.197	0.183	0.169	0.163
X0 Zero Sequence Reactance	0.017	0.016	0.015	0.012	0.019	0.018	0.017	0.016
Unsaturated Values in Per Unit at Base Ratings and Voltages								
Xd Dir. Axis Synchronous	2.433	2.268	2.107	1.745	2.744	2.544	2.353	2.262
X'd Dir. Axis Transient	0.168	0.156	0.145	0.120	0.189	0.175	0.162	0.156
X''d Dir. Axis Subtransient	0.138	0.129	0.120	0.099	0.156	0.144	0.134	0.128
Xq Quad. Axis Reactance	1.880	1.753	1.629	1.349	2.121	1.966	1.819	1.748
X''q Quad. Axis Subtransient	0.342	0.319	0.297	0.246	0.386	0.358	0.331	0.318
XL Stator Leakage Reactance	0.075	0.070	0.065	0.054	0.085	0.079	0.073	0.070
Xlr Rotor Leakage Reactance	0.085	0.079	0.074	0.061	0.096	0.089	0.082	0.079
X2 Negative Sequence Reactance	0.210	0.196	0.182	0.150	0.237	0.219	0.203	0.195
X0 Zero Sequence Reactance	0.020	0.019	0.017	0.014	0.023	0.021	0.019	0.019

* Parallel Star connection only available with 12 leads winding option

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Time Constants (Seconds)		
T'd Transient Time Const.	0.088	
T''d Sub-Transient Time Const.	0.015	
T'do O.C. Field Time Const.	3.63	
Ta Armature Time Const.	0.025	
T''q Sub-Transient Time Const.	0.01	
Resistances in Ohms (Ω) at 22°C		
Stator Winding Resistance (Ra), per phase for series connected	0.00210	
Rotor Winding Resistance (Rf)	1.82	
Exciter Stator Winding Resistance	18.47	
Exciter Rotor Winding Resistance per phase	0.095	
PMG Phase Resistance (Rpmg) per phase	1.91	
Positive Sequence Resistance (R1)	0.00263	
Negative Sequence Resistance (R2)	0.00302	
Zero Sequence Resistance (R0)	0.00263	
Saturation Factors	400V	480V
SG1.0	0.528	0.537
SG1.2	2.099	1.879
Mechanical Data		
Shaft and Keys	All alternator rotors are dynamically balanced to better than ISO 21940-11 Grade 2.5 for minimum vibration in operation. Two bearing generators are balanced with a half key.	
	1 Bearing	2 Bearing
SAE Adaptor	SAE0,1	SAE0,1
Moment of Inertia	19 kgm ²	18.5 kgm ²
Weight Wound Stator	924kg	924kg
Weight Wound Rotor	800kg	758kg
Weight Complete Alternator	1953kg	2030kg
Shipping weight in a Crate	1996kg	2073kg
Packing Crate Size	160x105x153(cm)	160x105x153(cm)
Maximum Over Speed	2250 RPM for two minutes	
Bearing Drive End	-	BALL 6224
Bearing Non-Drive End	BALL 6317	BALL 6317

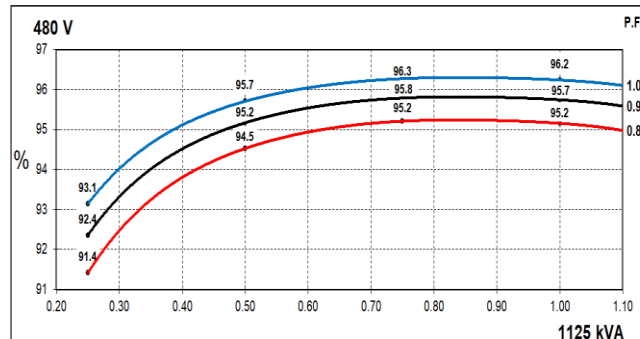
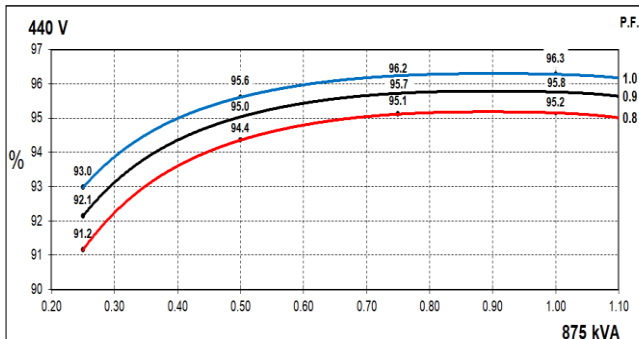
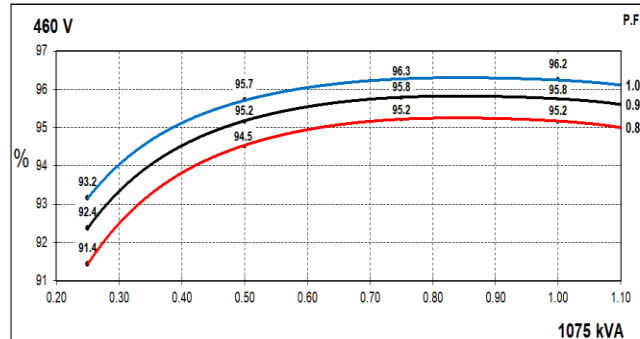
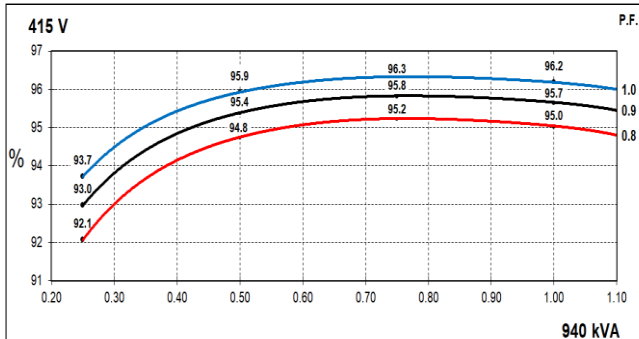
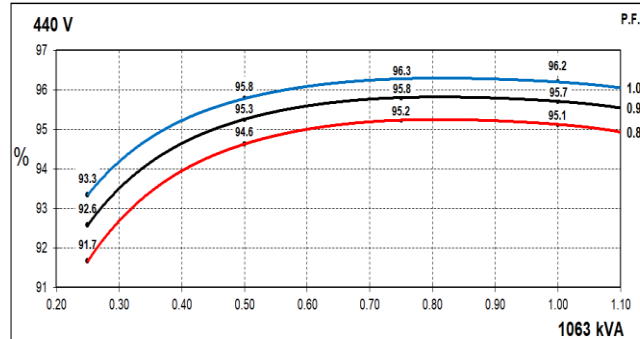
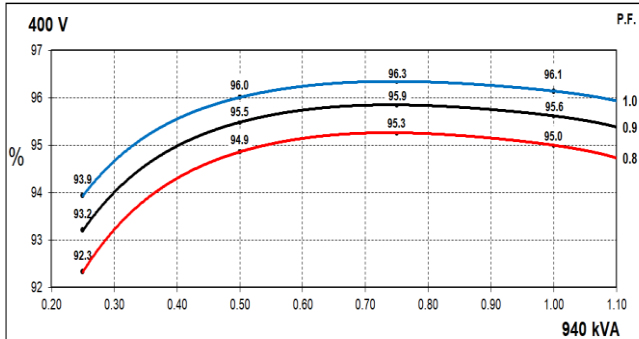
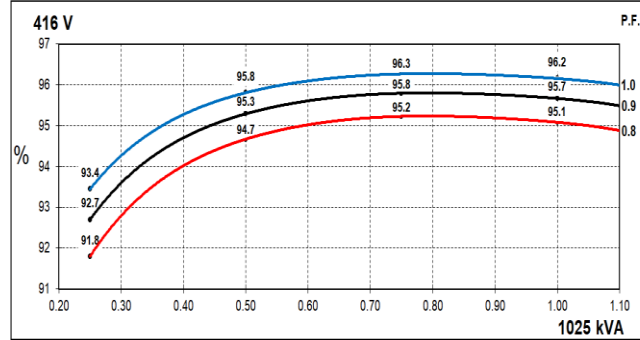
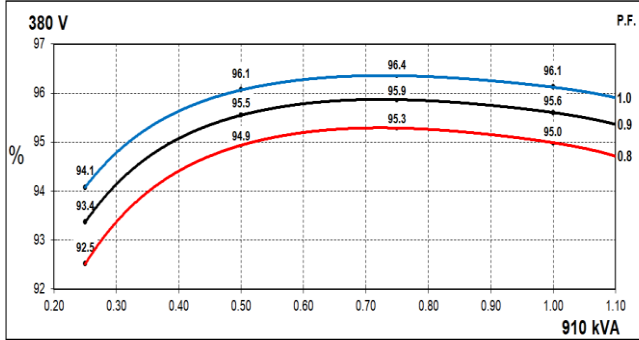
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THREE PHASE EFFICIENCY CURVES

50Hz

60Hz

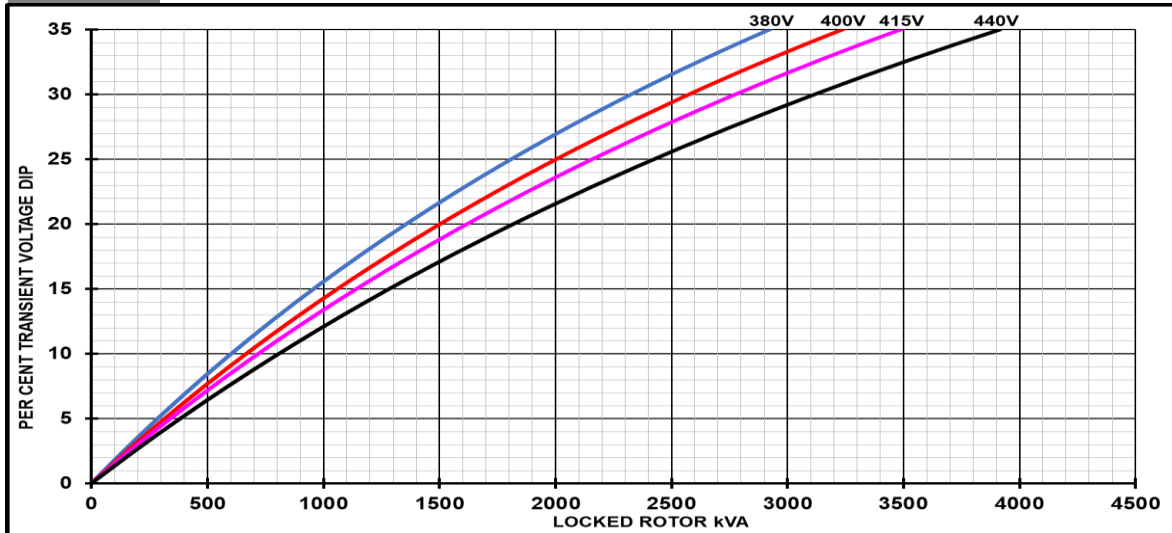


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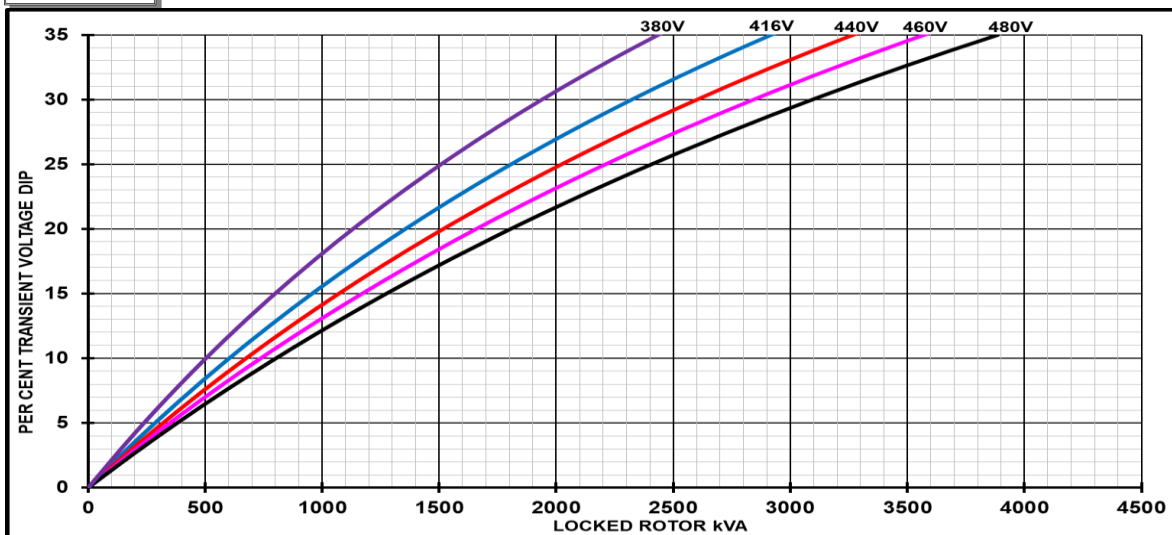
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Locked Rotor Motor Starting Curves - Separately Excited

50Hz



60Hz



Transient Voltage Dip Scaling Factor		Transient Voltage Rise Scaling Factor	
Lagging PF	Scaling Factor	Lagging PF	Scaling Factor
<= 0.4	1.00	<= 0.4	1.25
0.5	0.95	0.5	1.20
0.6	0.90	0.6	1.15
0.7	0.86	0.7	1.10
0.8	0.83	> 0.7	1.00
0.9	0.75		
0.95	0.70		
1	0.65		

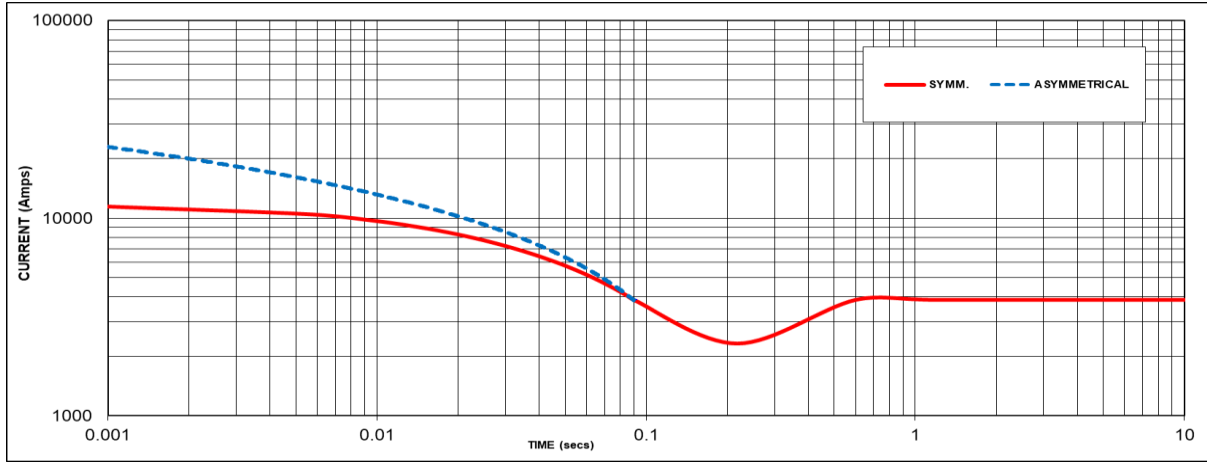
Note: To determine % Transient Voltage Dip or Voltage Rise at various PF, multiply the % Voltage Dip from the curve directly by the Scaling Factor.

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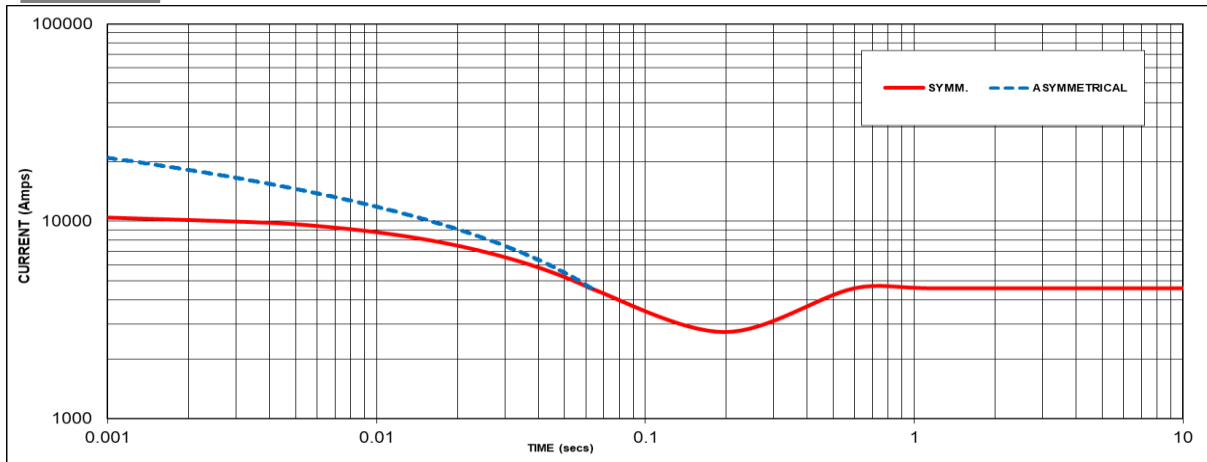
Three-phase Short Circuit Decrement Curve - Separately Excited

50Hz



60Hz

Sustained Short Circuit = 3859 Amps



Sustained Short Circuit = 4591 Amps

Note 1

The following multiplication factors should be used to adjust the values from curve between time 0.001 seconds and the minimum current point in respect of nominal operating voltage :

50Hz		60Hz	
Voltage	Factor	Voltage	Factor
380V	X 1.00	416V	X 1.00
400V	-	440V	-
415V	-	460V	-
440V	-	480V	-

The sustained current value is constant irrespective of voltage level

If MX322 or digital AVR is used, the sustained short-circuit current value is to be multiplied by a factor of 1.1.

Note 2

The following multiplication factor should be used to convert the values calculated in accordance with NOTE 1 to those applicable to the various types of short circuit :

	3-phase	2-phase L-L	1-phase L-N
Instantaneous	x 1.00	x 0.87	x 1.30
Minimum	x 1.00	x 1.80	x 3.20
Sustained	x 1.00	x 1.50	x 2.50
Max. sustained duration	10 sec.	5 sec.	2 sec.

Note 3

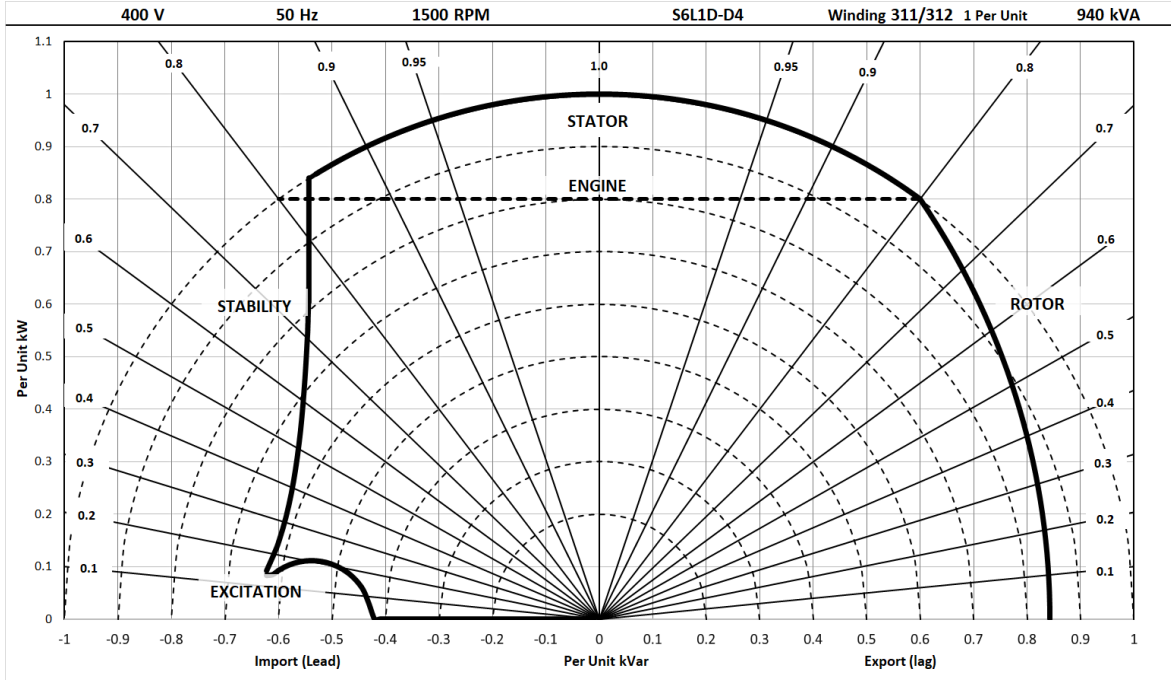
All other times are unchanged
 Curves are drawn for Star connections under no-load excitation at rated speeds. For other connection (where applicable) the following multipliers should be applied to current values as shown :
 Parallel Star = Curve current value X 2
 Series Delta = Curve current value X 1.732

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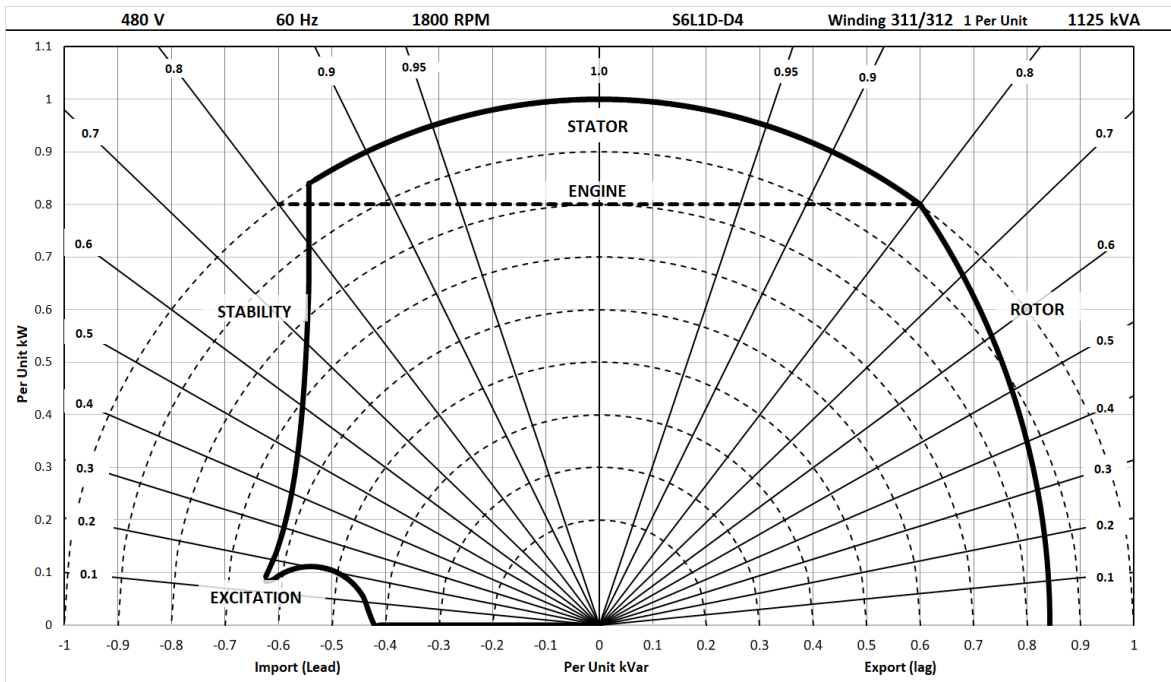
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Typical Alternator Operating Charts

400V/50Hz



480V/60Hz



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RATINGS AT 0.8 POWER FACTOR

Class - Temp Rise		Standby - 163/27°C				Standby - 150/40°C				Cont. H - 125/40°C				Cont. F - 105/40°C			
50 Hz	Star (V)	380	400	415	440	380	400	415	440	380	400	415	440	380	400	415	440
	Parallel Star (V)*	190	200	208	220	190	200	208	220	190	200	208	220	190	200	208	220
	Delta (V)	220	230	240	254	220	230	240	254	220	230	240	254	220	230	240	254
	kVA	1000	1010	1010	960	960	980	980	920	910	940	940	875	830	860	860	800
	kW	800	808	808	768	768	784	784	736	728	752	752	700	664	688	688	640
	Efficiency (%)	94.7	94.8	94.9	95.0	94.9	94.9	95.0	95.1	95.0	95.0	95.0	95.2	95.1	95.1	95.2	95.2
	kW Input	844	852	851	808	810	826	826	774	766	792	791	736	698	723	723	672

60 Hz	Star (V)	416	440	460	480	416	440	460	480	416	440	460	480	416	440	460	480
	Parallel Star (V)*	208	220	230	240	208	220	230	240	208	220	230	240	208	220	230	240
	Delta (V)	240	254	266	277	240	254	266	277	240	254	266	277	240	254	266	277
	kVA	1125	1163	1175	1219	1088	1125	1138	1188	1025	1063	1075	1125	915	965	1000	1025
	kW	900	930	940	975	870	900	910	950	820	850	860	900	732	772	800	820
	Efficiency (%)	94.9	95.0	95.0	95.0	95.0	95.0	95.1	95.1	95.1	95.1	95.2	95.2	95.2	95.2	95.2	95.2
	kW Input	948	980	989	1026	916	947	957	1000	862	894	904	946	769	811	840	861

* Parallel Star connection only available with 12 leads winding option

De-rates

All values tabulated above are subject to the following reductions:

- 5% when air inlet filters are fitted
- 3% for every 500 meters by which the operating altitude exceeds 1000 meters above mean sea level
- 3% for every 5°C by which the operational ambient temperature exceeds 40°C @ Class H temperature rise (please refer to applications for ambient temperature de-rates at other temperature rise classes)
- For marine alternators, 3% for every 5°C by which the operational ambient temperature exceeds 50°C
- For any other operating conditions impacting the cooling circuit please refer to applications

Note: Requirement for operating in an ambient exceeding 60°C and altitude exceeding 4000 meters (for <690V) or 1500 meters (for >690V) must be referred to applications.

Dimensional and Torsional Drawing

For dimensional and torsional information please refer to the alternator General Arrangement and rotor drawings available on our website (<http://stamford-avk.com/>)

Note: Continuous development of our products means that the information contained in our data sheets can change without notice, and specifications should always be confirmed with Cummins Generator Technologies prior to purchase.



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